

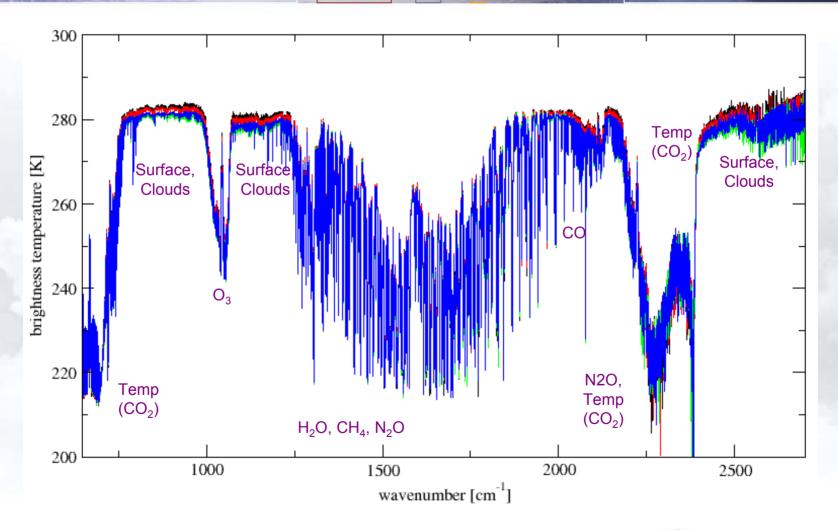
Operational IASI Level 2 Processing

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First IASI spectra on 29 November 2006 L1 Products operational since 29 May 2007





IASI level 2 product generation

IASI Level 1c AVHRR Cloud Mask and S/CTT

Configurable Databases

ATOVS Level 2

AMSU-A Level 1

MHS Level 1

NWP Forecast

Pre-Processing

Cloud Processing

Geophysical Parameters Retrieval

Monitoring Information

Level 2 Product

Quality Information

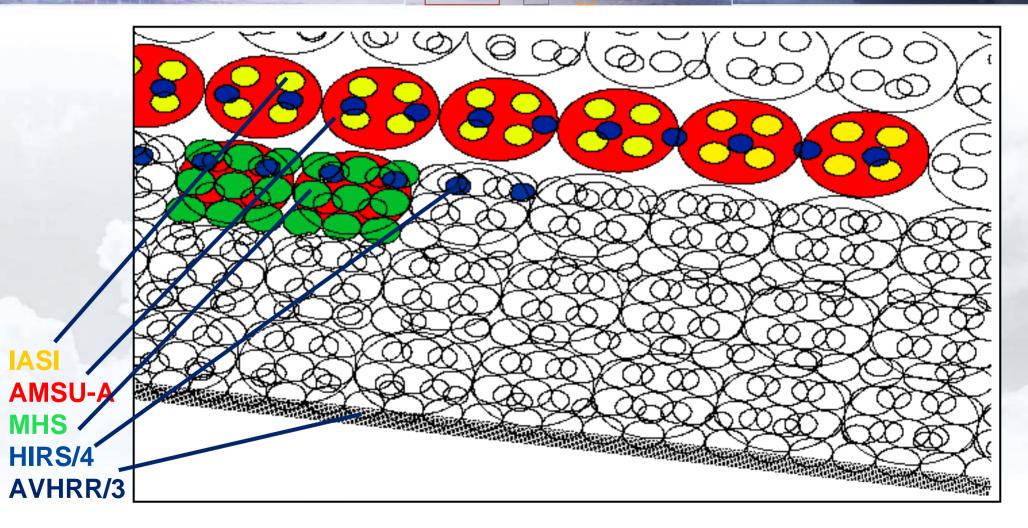


Properties of the Operational IASI L2 Processor (1/3)

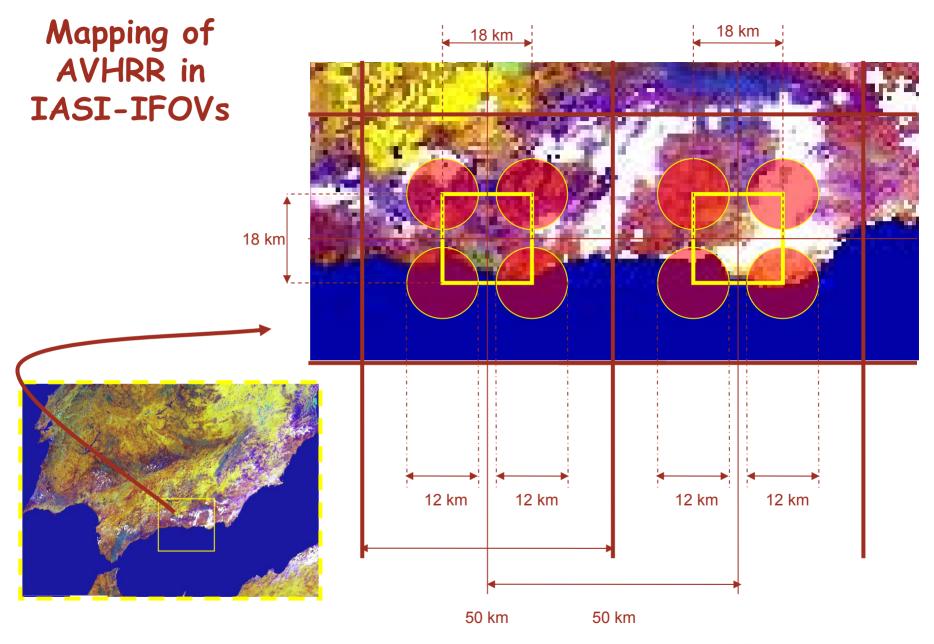
- For a best use of IASI measurements the level 2 processing combines IASI with concurrent measurements of AVHRR and AMSU-A to detect clouds and to derive cloud parameters
- IASI stand-alone processing is used for geophysical parameters retrieval
- Inclusion of NWP forecast
 - Surface pressure as reference for the profiles to be retrieved
 - Surface wind speed over sea for the calculation of surface emissivity
 - Temperature and water-vapour profiles for cloud detection and CO₂-slicing
 - No conditioning of profile retrieval with NWP forecast



Scan patterns of the instruments









Properties of the Operational IASI L2 Processor (2/3)

- Processing is steered by configuration settings (80 configurable auxiliary data sets),
 which allows for optimisation of PPF
 - Most of the settings have been refined during commissioning, based on validation results
- Online quality control supports the choice of best processing options in case of partly unavailable IASI data or corrupt side information (data from other instruments or NWP forecast)
- A number of flags are generated steering through the processing and giving quality indicators; 42 flags are specified, which are part of the product, a sub-selection directly relevant for the user is disseminated with the product; an error covariance (or part of it) will be included in future



Properties of the Operational IASI L2 Processor (3/3)

- Different retrieval methods are implemented so that the best configuration can be chosen based on validation results and operational constraints:
 - EOF regression retrieval for temperature and moisture retrieval, surface temperature, emissivity, and ozone columns
 - Artificial neural network retrieval using a selection of spectral samples for trace gas retrievals
 - Iterative retrieval using a selection of spectral samples for temperature and humidity profiles as well as surface and cloud parameters
- The retrieval can be configured to chose among the retrieval schemes or to combine them



Geophysical parameters retrieval: state vector to be derived

- The state vector to be retrieved consists of the following parameters
 - Temperature profile at high vertical resolution
 - Water vapour profile at high vertical resolution
 - Ozone columns in deep layers (0-6km, 0-12 km, 0-16 km, total column)
 - Land or sea surface temperature
 - Surface emissivity at 12 spectral positions
 - Columnar amounts of N₂O, CO, CH₄, CO₂
 - Cloud amount
 - Cloud top temperature and pressure
 - Cloud phase
- In case of clouds and elevated surface the state vector has to be modified
- The iterative retrieval provides error covariances, part of it is included in the product

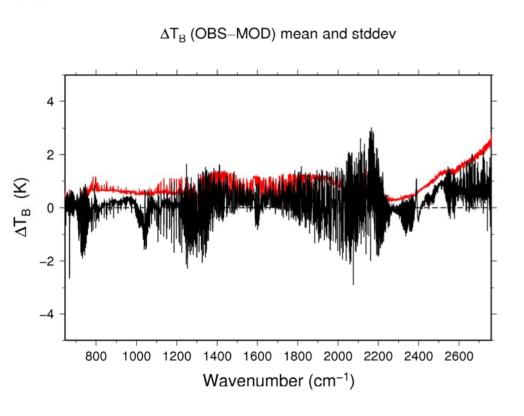


Preprocessing

- Validation of incoming data
 - Examination of quality flags in IASI L1C, AMSU-A, MHS, AVHRR Scenes Analysis
 - Check of radiances against valid bounds
 - Check of geolocation against valid bounds
 - Check of NWP forecast against valid bounds and for completeness
- Mapping of AMSU-A, MHS, AVHRR, and NWP to IASI IFOV
- Extraction of land-sea mask and surface topography and mapping to IASI IFOV
- Bias correction of IASI radiances
- Correction for ISRF shift in case of inhomogeneous scenes
- Calculation of IPSF-weighted fractional cloud cover from AVHRR
- Calculation of IPSF-weighted surface and cloud top temperatures from AVHRR

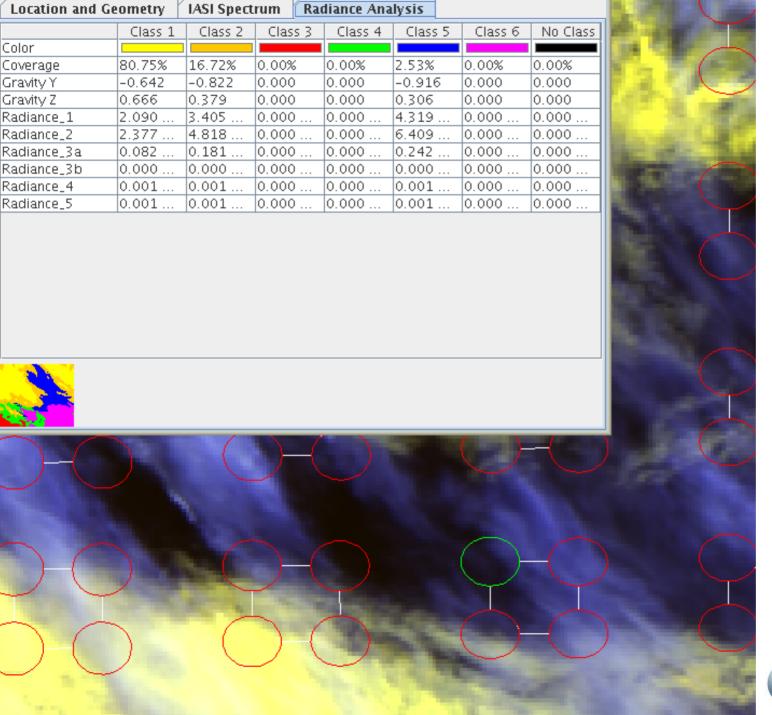


Correction of systematic errors



- Retrieval, CO₂-slicing, and cloud detection use radiative transfer calculations as basis
- Prerequisite for the functionality of the retrieval is a good representativity of the measurements by simulated radiances
- Systematic errors:
 - Approxmations necessary for fast calculations
 - Insufficient knowledge of spectroscopic data
 - Erroneous input data
- Systematic fit of models to IASI measurements





AVHRR Radiance
Analysis
inside IASI



Cloud processing: cloud detection

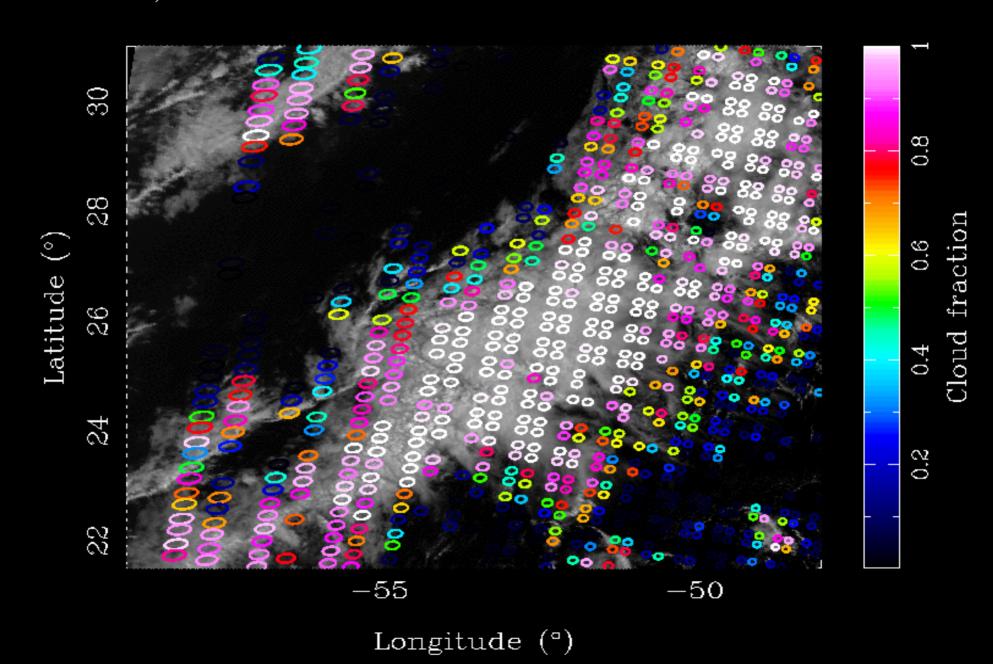
- AVHRR-based cloud detection using Scenes Analysis from AVHRR Level 1 processing
- Combined IASI / ATOVS cloud detection: 2 inter-channel regression methods
- IASI stand-alone cloud detection
 - Window-channel test based on calculated clear-sky radiance spectra
 - 2 IASI inter-channel regression tests
 - Horizontal coherence test
 - Thresholds on principal component scores
 - Window cross-correlation test
 - Threshold test for clouds over elevated polar regions
 - Threshold test for detection of dust storms



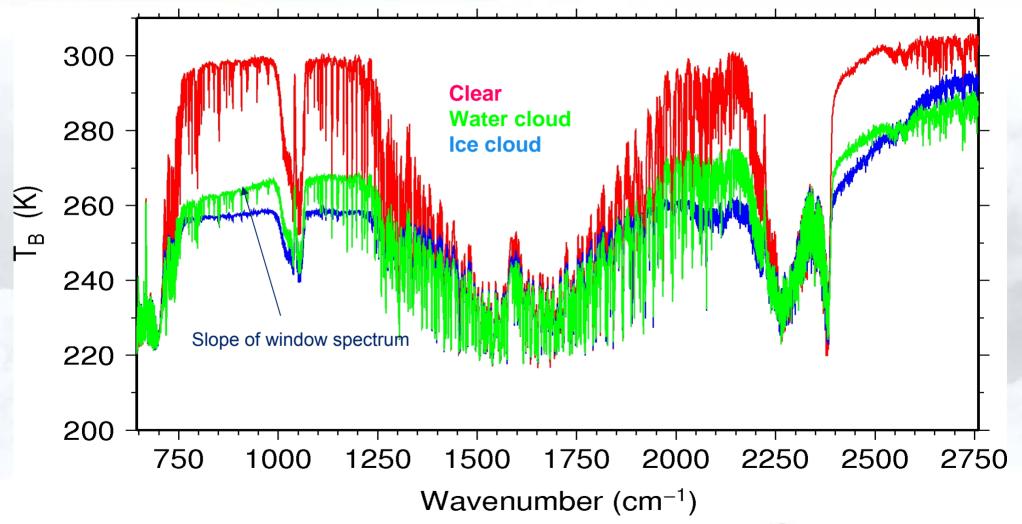
Cloud processing: cloud parameters retrieval

- Cloud fraction (CO₂-Slicing)
- Cloud top pressure and temperature (CO₂-Slicing)
- Cloud phase: examination of slope of window spectra





Discrimination of ice and water clouds





Geophysical parameters retrieval (1/2)

- An EOF regression retrieval using 500 principal component scores representing the spectra of bands 1 and 2 for temperture and humidity retrieval, surface temeprature, land surface emissivity, and ozone columns
- An artificial neural network retrieval is based on a selection of IASI spectral samples and a guess temperature profile; the derived parameters are CO, CH₄, N₂O, CO₂
- An iterative maximum probability retrieval, based on the Levenberg-Marquardt iteration utilising 235 spectral samples
- Band 3 has been removed from temperature and humidity sounding
 - Insufficient capabilities to include solar radiation (too time consuming)
 - NLTE effects not modeled
 - Suffers from high noise compared to bands 1 and 2



Geophysical parameters retrieval (2/2)

- Iterative retrieval
 - Initialised with results from the first retrievals (EOF regression, ANN) and cloud parameters from CO₂-slicing
 - Background from climatology
 - Includes K-matrix version of RTIASI-4
- Different conditions require modification of state vector
 - Full state vector without cloud parameters in clear situations
 - Reduced state vector in case of elevated surface
 - Full state vector including cloud parameters in case of slightly cloudy conditions (< 20% cloud coverage)
 - Reduced state vector when cloud fraction exceeds 20%, retrieval only above cloud top
- Simultaneaous retrieval of all state vector elements
 - Operational contraints allow currently only for 5 iterations (non-convergence in some cases)



Flag collection (1/2)

- A collection of 42 flags is part of the product
- Very important information for the user
 - Which data, in which quality entered the product generation?
 - Which methods have been used and how was the product generated?
 - What is the product quality?
- Examination of the flags is mandatory in the utilisation of the product
 - Ignorance of the flags will lead to dissatisfaction of users

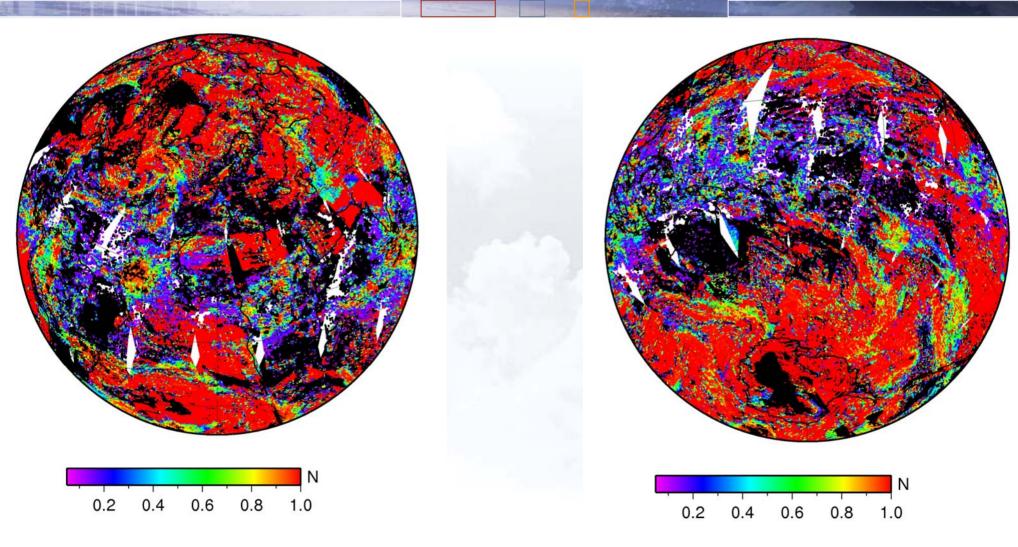


Flag collection (2/2)

- Validity and quality of the input data: 13 flags
- Information on cloud processing: 9 flags
- Information on day/night, sun-glint, land/sea: 3 flags
- Retrieval choice and settings: 8 flags
- Retrieval quality: 9 flags
- Definition of flags is given in
 - Annex D of the IASI L2 Product Generation Specification
 - Section 4.3.3 of the IASI L2 Products Guide



Cloud Cover - 16 October 2007





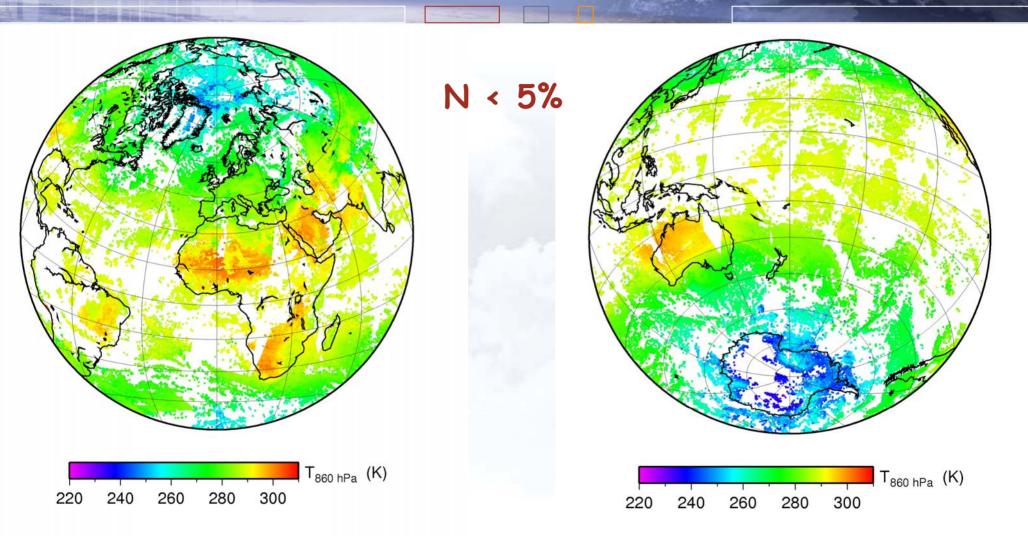


Number of Soundings in Global Datasets

- IASI soundings are possible in clear or nearly clear fields of view
 - Clear retrievals are best
 - Gradual degradation of retrievals below cloud top with increasing cloud amount
 - Retrievals above cloud top are almost as good as clear ones
- The fraction of clear or almost clear IASI soundings:
 - N < 2%: 15% (varies between 12 and 24% among different orbits)</p>
 - N < 5%: 16%
- Fraction of useful soundings depending on atmospheric level
 - 860 hPa: 52%
 - 700 hPa: 54%
 - 500 hPa: 62%
 - 300 hPa: 90%
 - 200 hPa: 95%

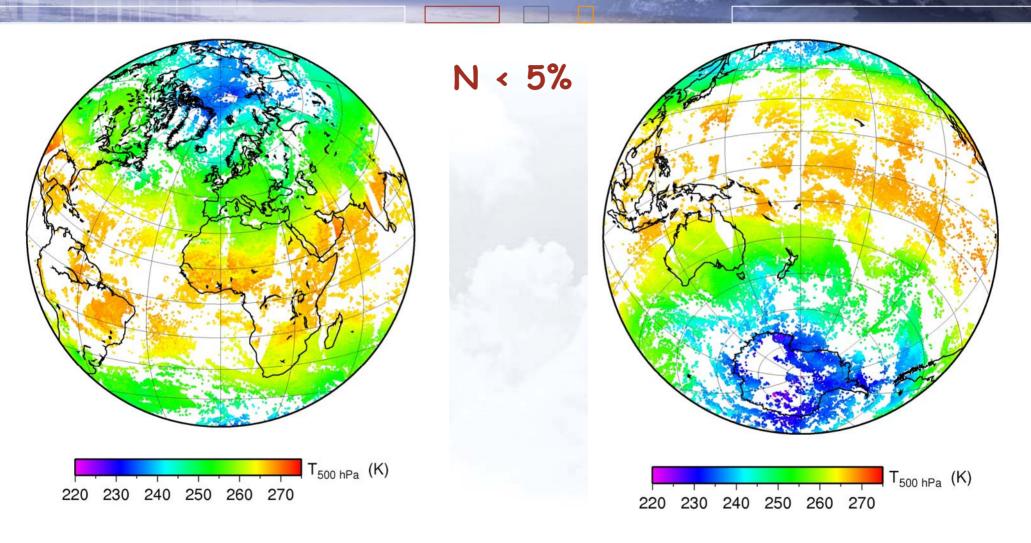


Temperature at 860 hPa: 16 October 2007



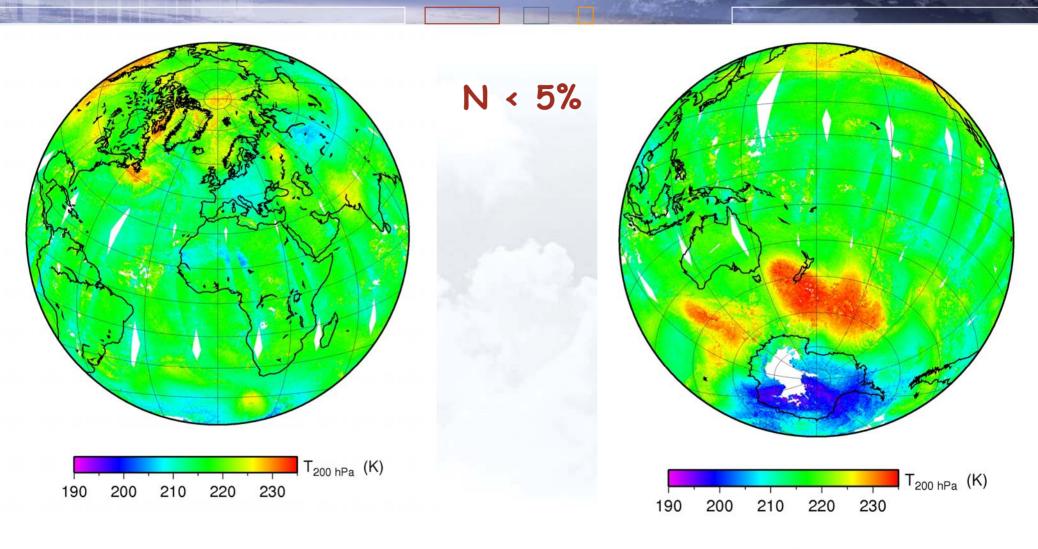


Temperature at 500 hPa: 16 October 2007



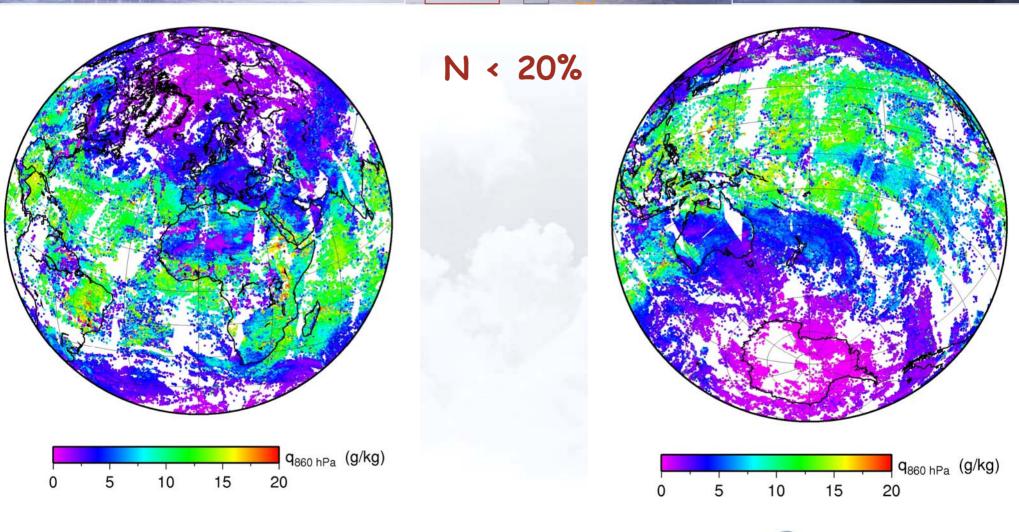


Temperature at 200 hPa: 16 October 2007





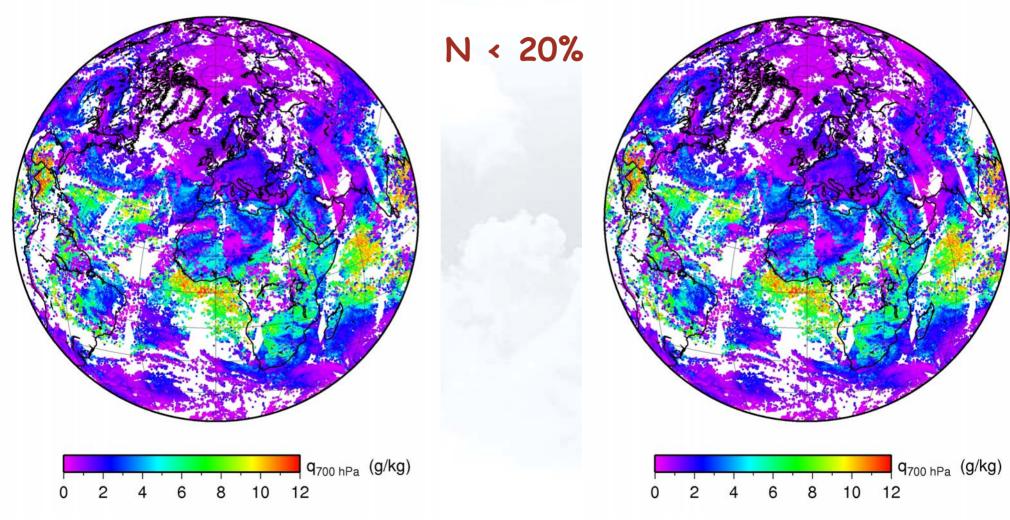
Specific Humidity at 860 hPa: 16 October 2007







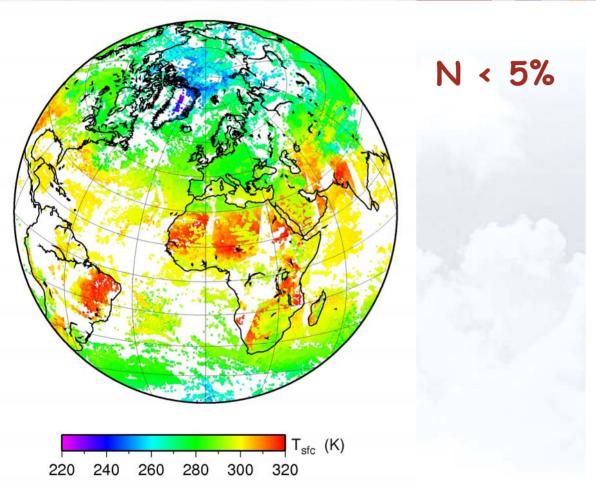
Specific Humidity at 700 hPa: 16 October 2007

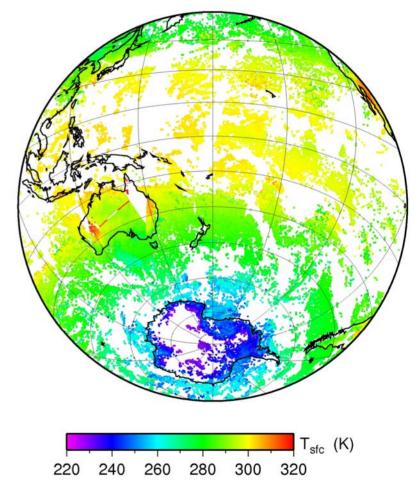


4th Workshop on Advanced High Spectral Resolution Infrared Observations EUM/MET/VWG/08/0380 Issue 1, 14/09/2008 Slide: 27



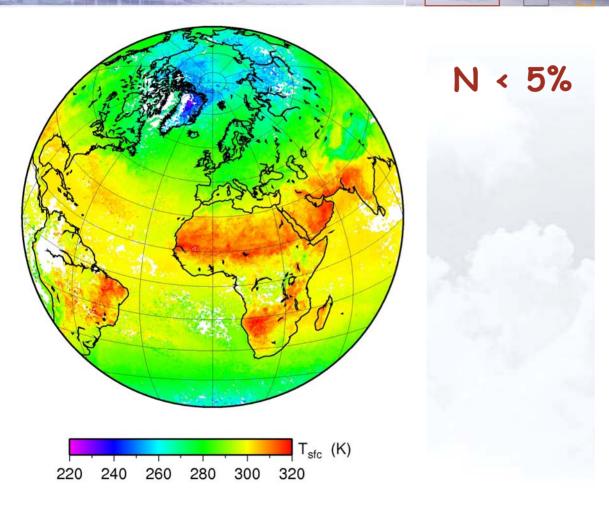
Surface Skin Temperature: 16 October 2007

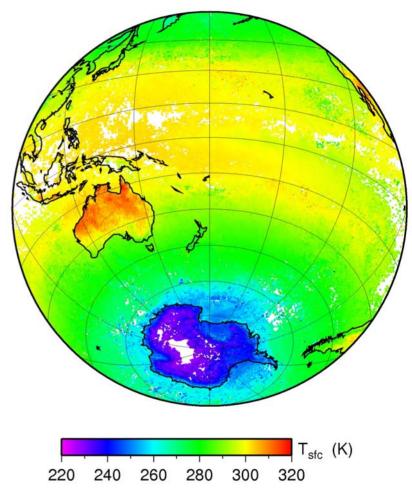






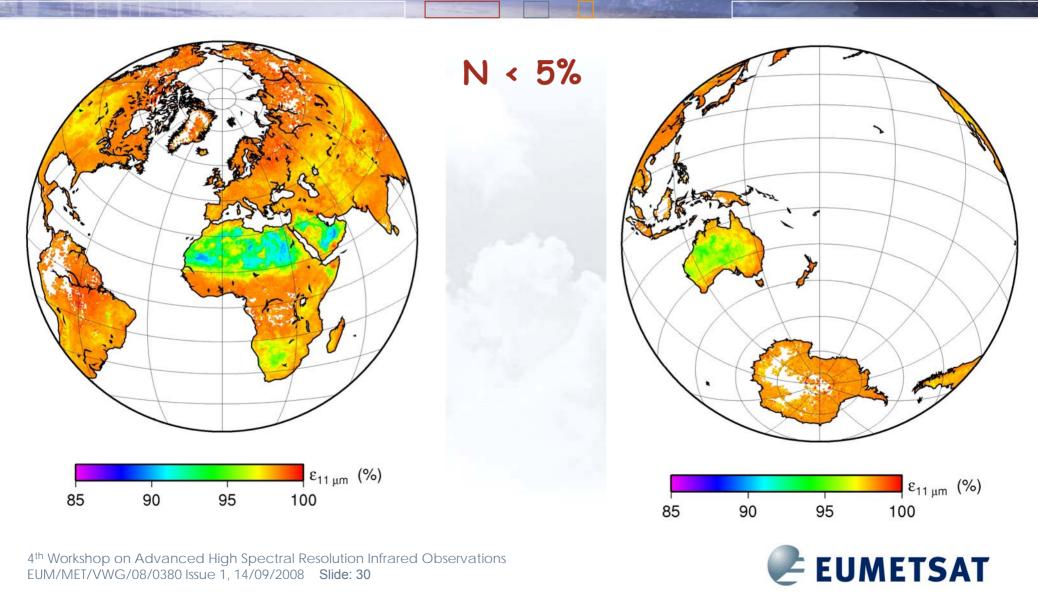
10 Day Average Sfc. Skin Temp.: 16-25 October 2007

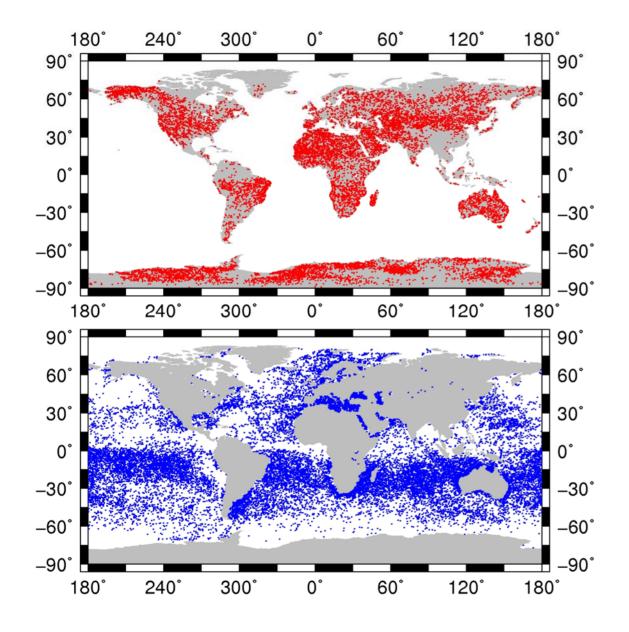






15 Day Average Emissivity at 11 µm: 16-30 October 2007





Comparison: ECMWF versus IASI

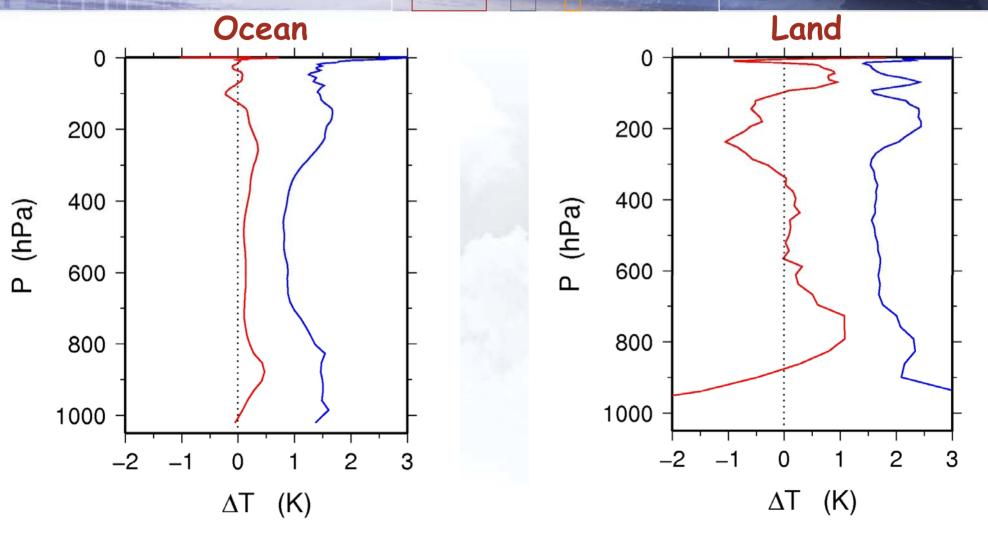
Clear situations May - June 2007

Land: 1330 match-ups

Ocean: 21810 match-ups

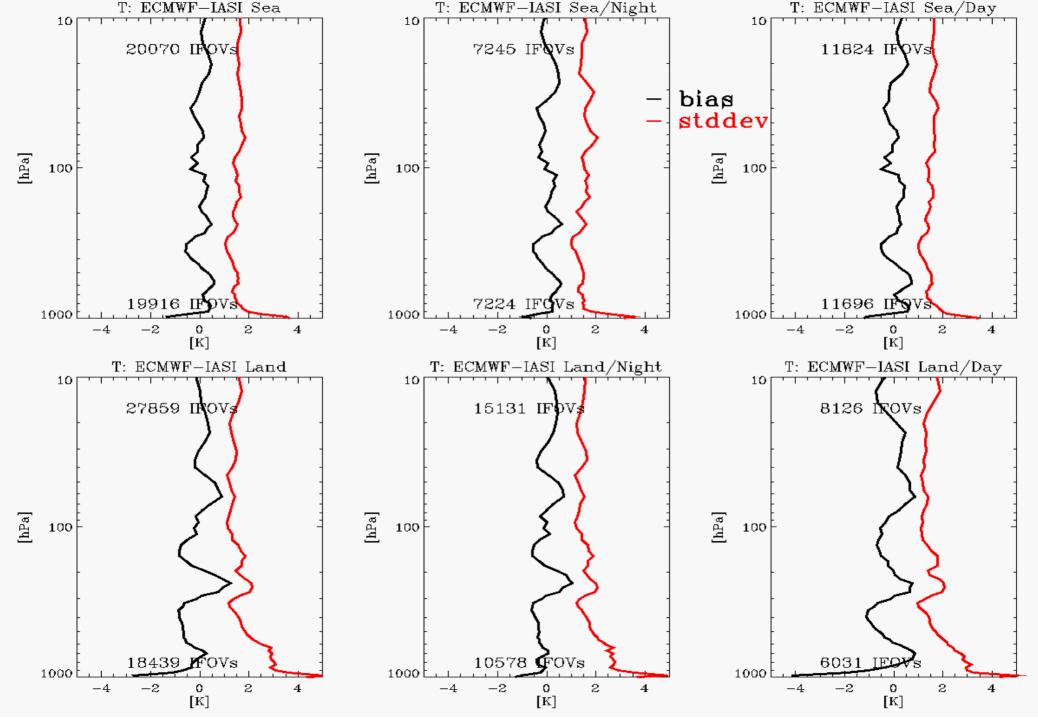


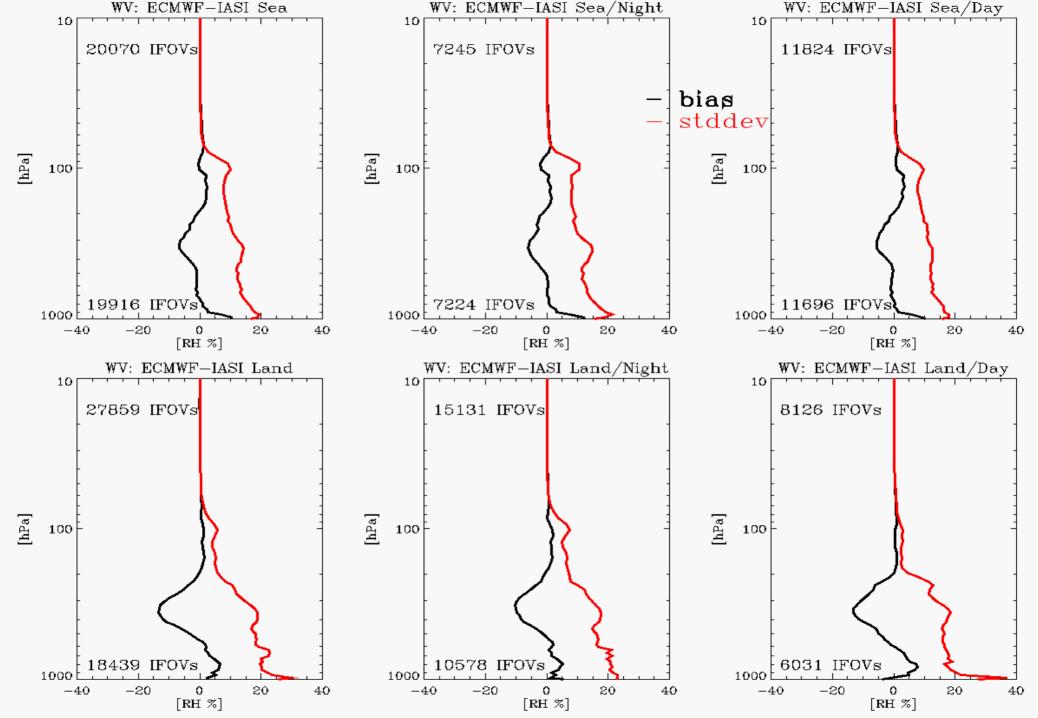
Comparison: ECMWF - IASI L2 (EOF regression)









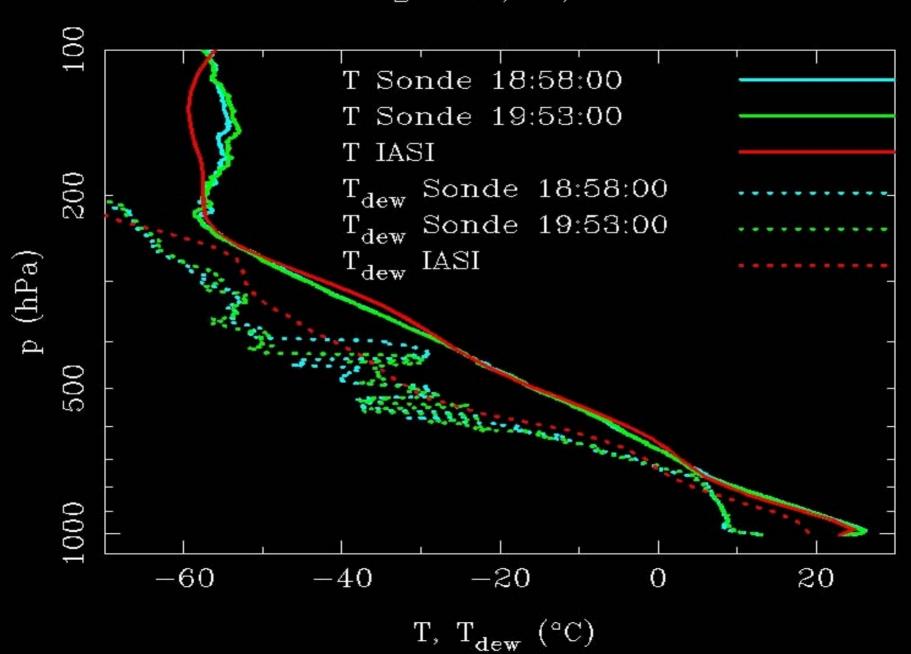


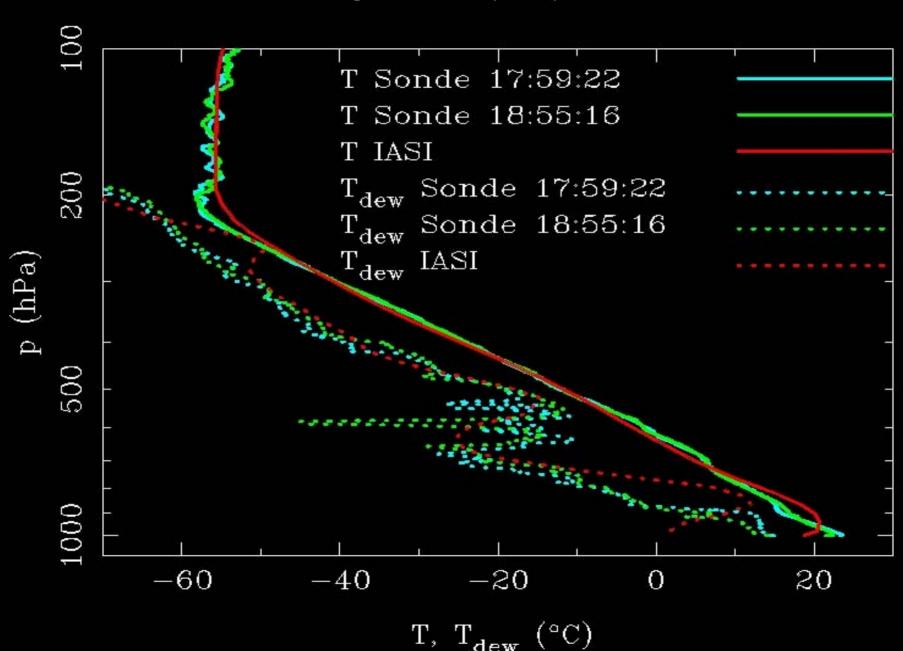
Validation Campaigns

- Met Office, airborne campaign, North Sea,
 - 2 February 2007
- JAIVEx, Gulf of Mexico, Oklahoma CART site
 - 18 April 4 May 2007
- RV Polarstern
 - 12 April 4 May 2007
 - 26 October 26 November 2007
- Arctic Observatory Sodankylä, FMI, Finland
 - 4 June 5 September 2007
- Richard Aßmann Observatory Lindenberg, DWD, Germany
 - 1 June 31 August 2007, continuing during clear situations
- See presentations by Xavier Calbet and Nikita Pougatchev



Lindenberg 2007/06/08 19:58:01

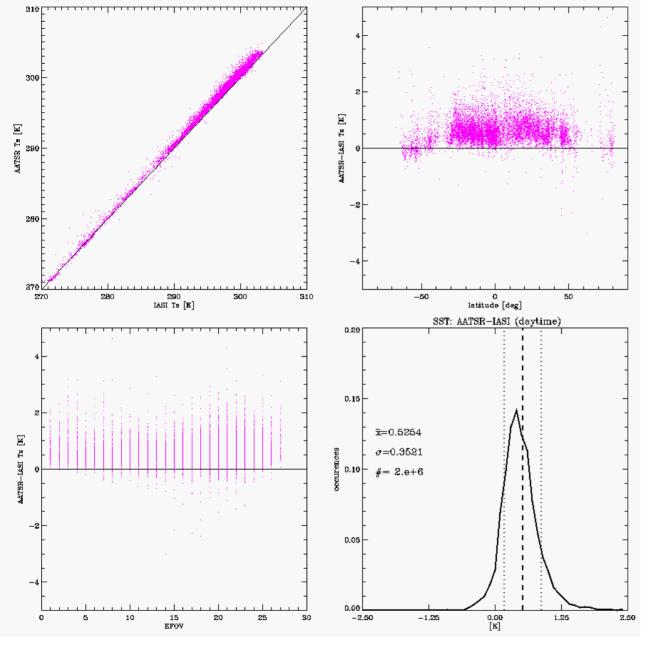




Systematic validation against radiosondes

- Considering components of the error budget is important to isolate errors in IASI retrieval
- Temporal variability of the atmosphere between IASI sounding and duration of the radiosonde ascent can be important when radiosonde is not launched closely to the satellite overpass
- Spatial variability of the atmosphere between IASI sounding and radiosonde trajectory is increased by displacement of the radiosonde during its ascent
- Errors in radiosonde measurements need to be characterised
- IASI profile retrievals are made on a fine vertical grid that is not compatible with the averaging kernels of the sounding
- See presentation by Nikita Pougatchev





Validation: SST, daytime against AATSR@Envisat

Bias: -0.52 K

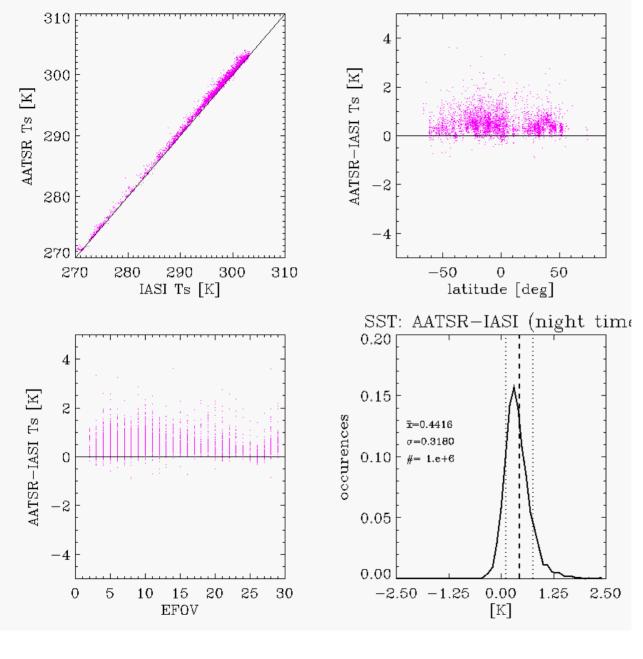
Std. Dev.: 0.35 K

Nb. Match-ups: 200000

20 orbits in 08/2007

 $\Delta t < 40 \text{ min}$





Validation: SST, nighttime against AATSR@Envisat

Bias: -0.44 K

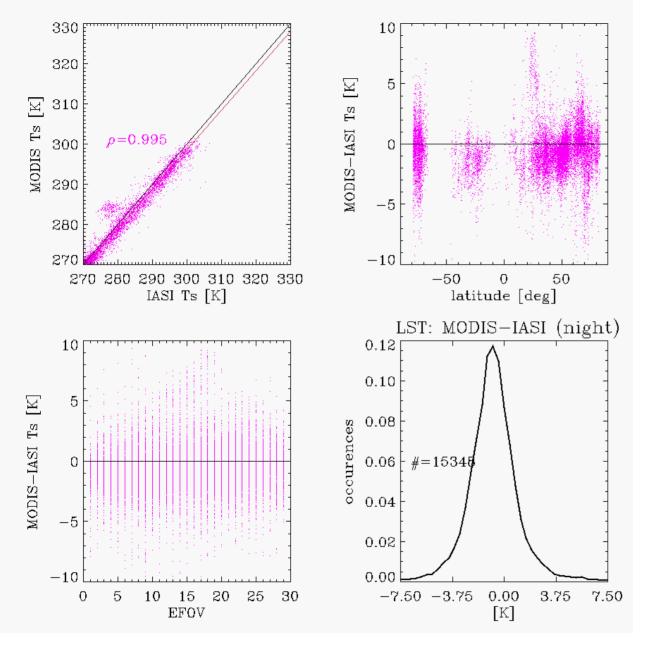
Std. Dev.: 0.32 K

Nb. Match-ups: 100000

20 orbits in 08/2007

 $\Delta t < 40 \text{ min}$





Validation: LST, nighttime against MODIS@Terra

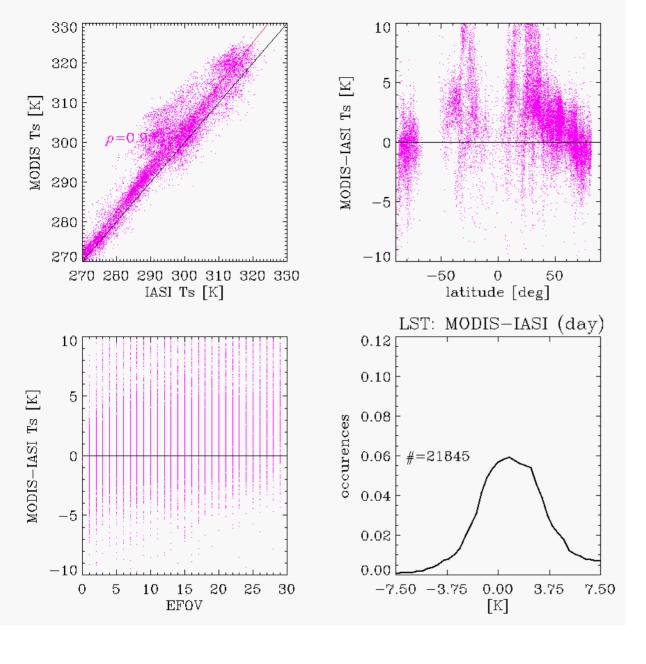
Bias: 0.5 K

Std. Dev.: 1.1 K

Nb. Match-ups: 15348

One day





Validation: LST, daytime against MODIS@Terra

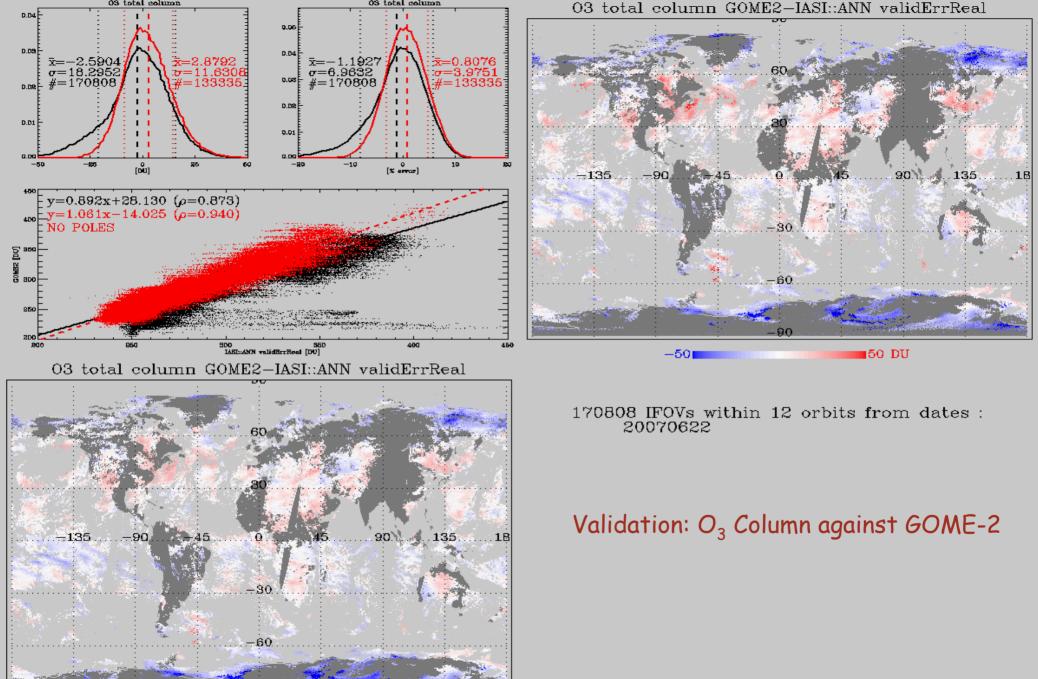
Bias: - 1.2 K

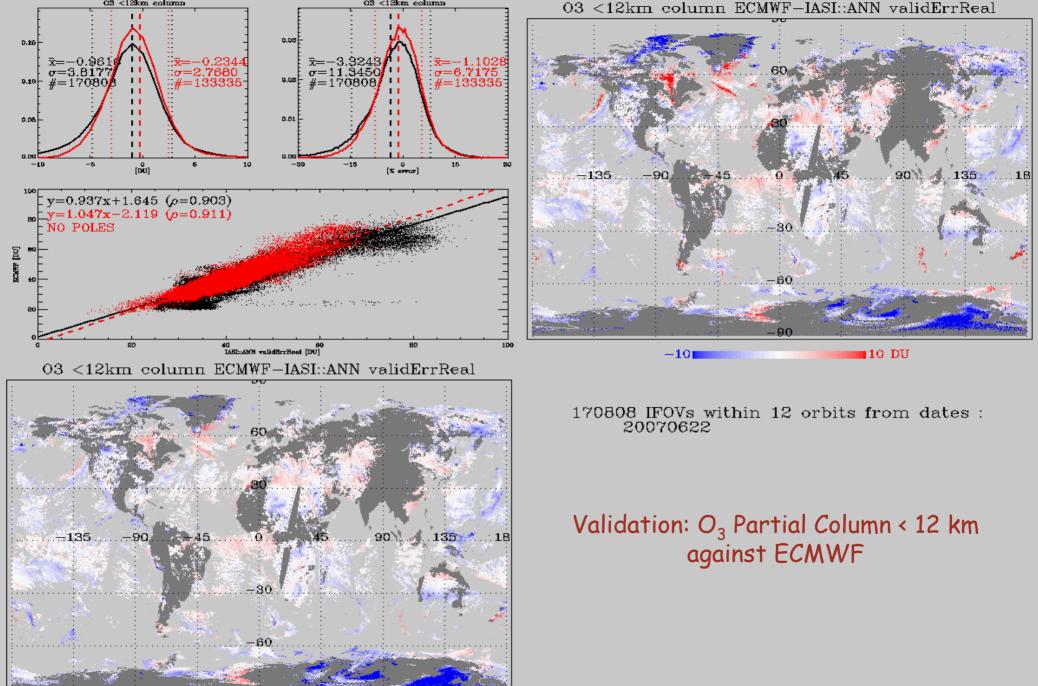
Std. Dev.: 2.2 K

Nb. Match-ups: 21845

One day







Dissemination to users

- IASI Level 1c data dissemination started on 29 May 2007
 - Full spectra via EumetCast and to NOAA
 - 300 selected spectral samples via GTS
- The IASI L2 NRT product is broken down into 5 streams:
 - TWT: Atmospheric temperature profiles, atmospheric water vapour profiles, surface skin temperature
 - OZO: Atmospheric ozone
 - CLP: Cloud parameters
 - TRG: Atmospheric trace gases CO, CH₄, N₂O, CO₂
 - EMS: Land surface emissivity
- IASI level 2 products are disseminated via EUMETCast and GTS
- The operational dissemination of level 2 products has started on 28 April 2008
- All products are accessible from the UMARF in native and HDF formats



Outlook

- Beyond the initial "day-1 processing" a number of construction areas exist
- Need for improvement of humidity retrievals
 - Possible separation of temperature and humidity retrievals
- Implementation faster radiative transfer model in iterative retrieval
 - Use of PCRTM
- Analysis of novel cloud detection and characterisation methods
 - Artificial neural networks
 - Variational cloud detection
- Work on improvement of cloudy retrievals
 - Inclusion of microwave soundings
 - Treatment on non-black clouds in iterative retrieval





more info: www.eumetsat.int

