



Climate
Change



Climate Data Record of Atmospheric Motion Vectors at EUMETSAT: Status and Perspective

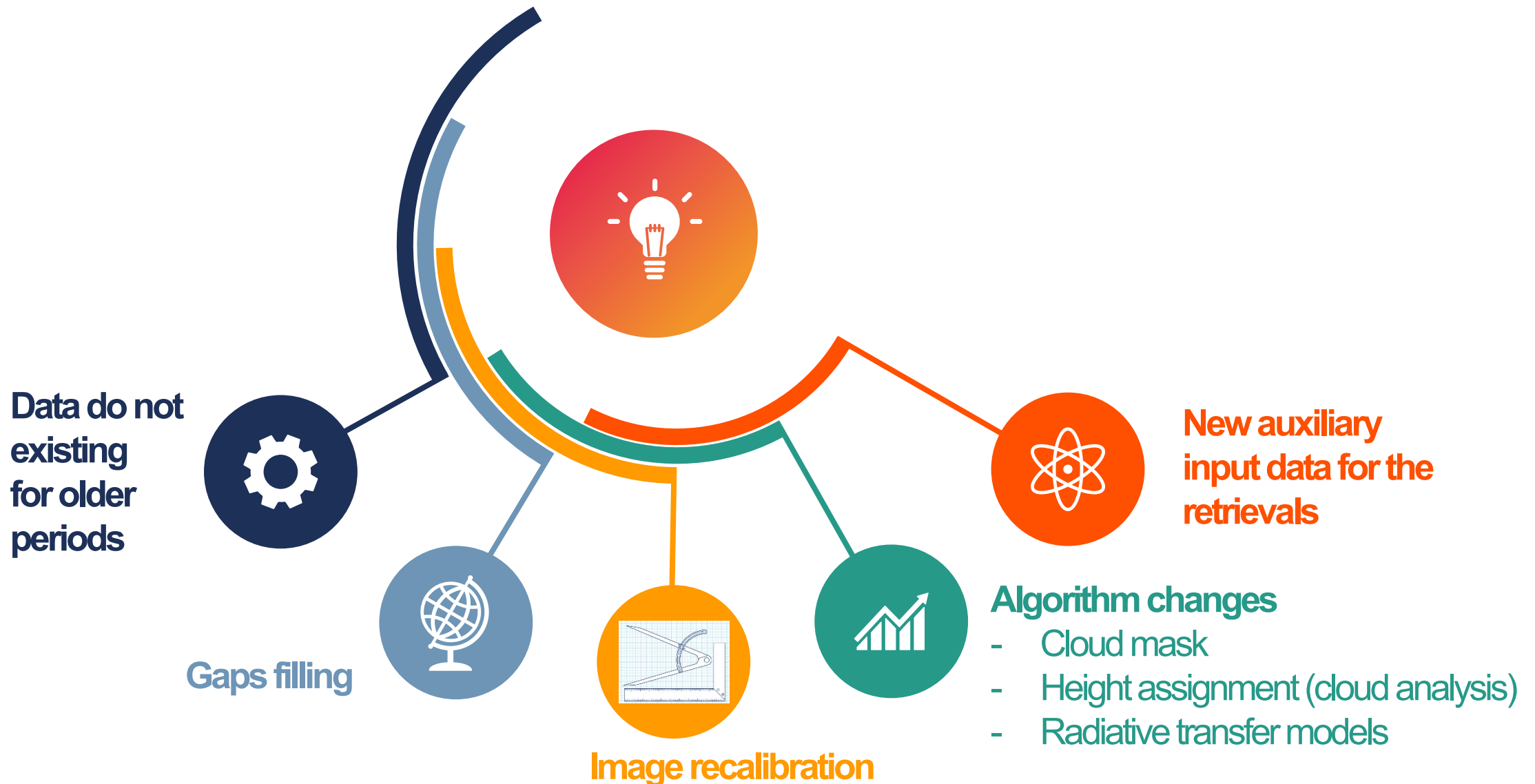
M. Doutriaux-Boucher, R. Huckle, A. Lattanzio, L. Medici
J. Onderwaater, J. Schulz, O. Sus, R. Borde, M.
Carranza, O. Hautecoeur



Outline

- ❑ Reprocessing of AMV: the need
 - ❑ GEO AMV
 - ❑ LEO AMVs
 - ❑ iCDR production
 - ❑ Future activities
-
- ❑ Next presentations by A. Lattanzio and R. Huckle will bring more details

Operational AMVs are archived but need to be reprocessed



Processing and validation/verification at EUMETSAT

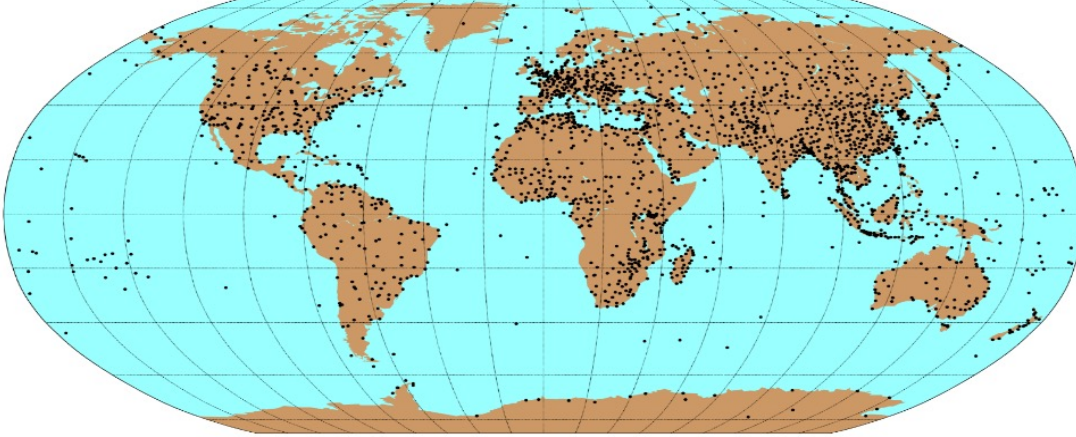
All AMV reprocessing is done at EUMETSAT

Validation is done using independent dataset such as

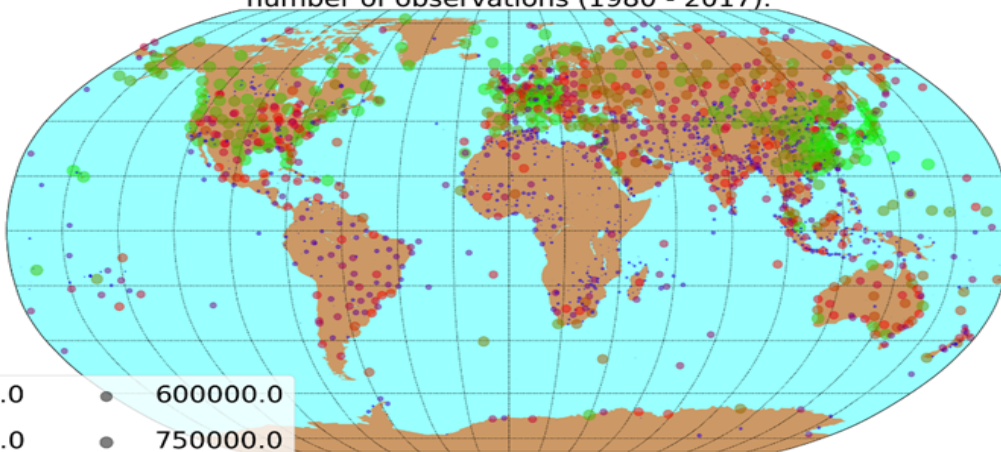
- ☐ ground base radiosonde
- ☐ other satellite data like MODIS AMVs
- ☐ model data

RAOBCORE radiosonde data over the period 1980-2017

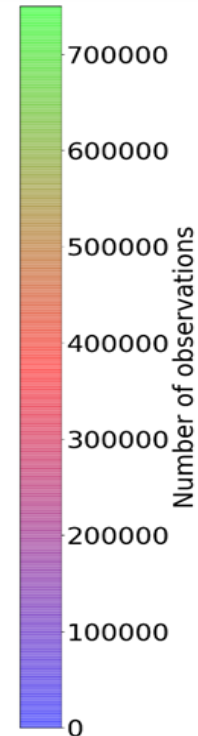
Locations of RAOBCORE radiosonde stations (n = 2283)



Locations of RAOBCORE radiosonde stations, scaled by number of observations (1980 - 2017).

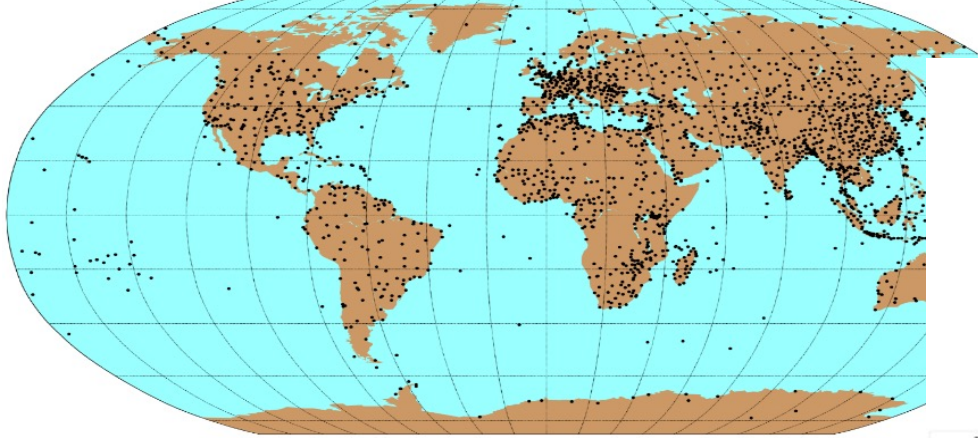


- 150000.0
- 300000.0
- 450000.0
- 600000.0
- 750000.0

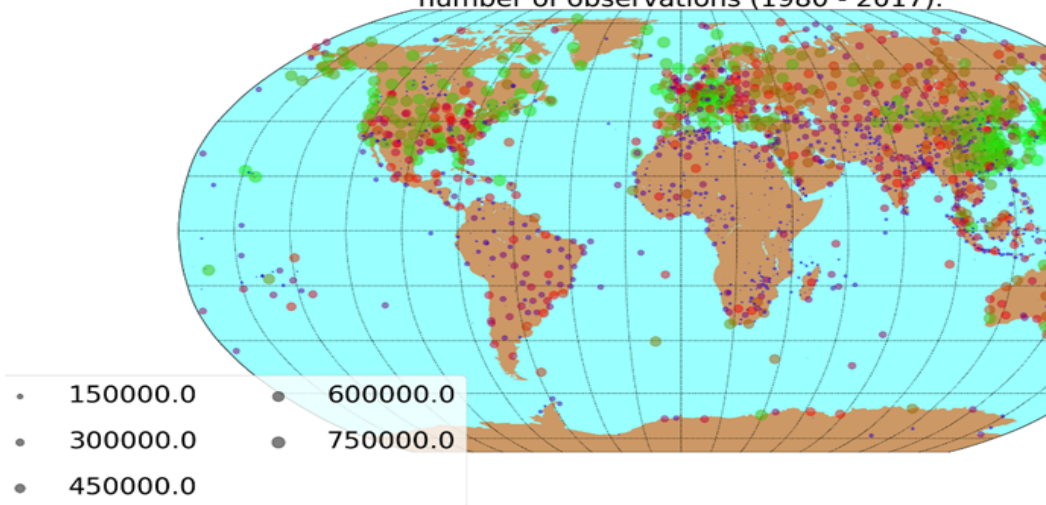


RAOBCORE radiosonde data over the period 1980-2017

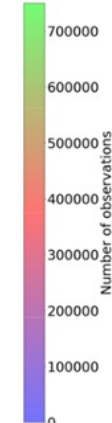
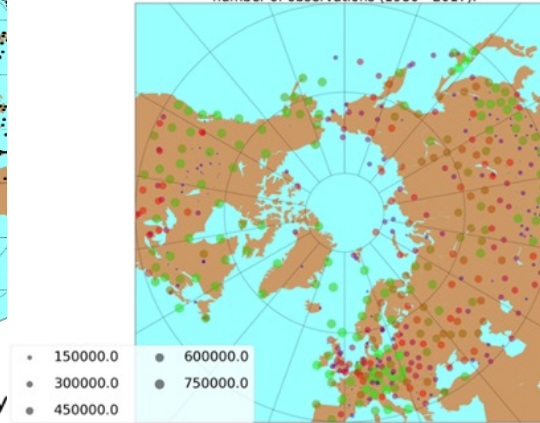
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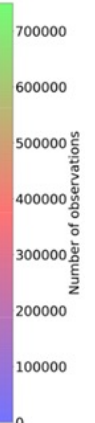
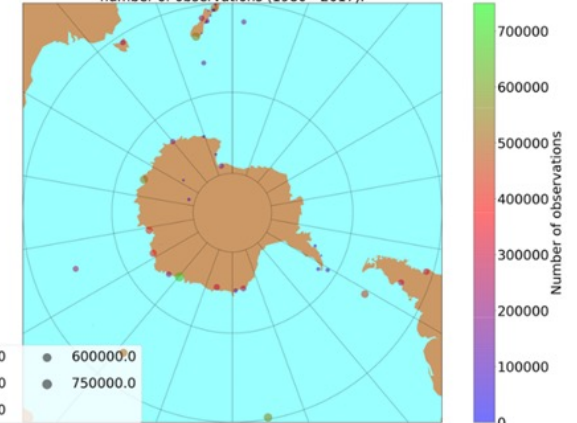
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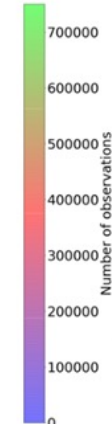
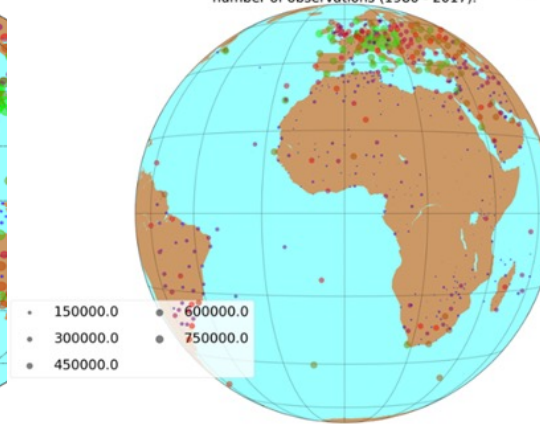
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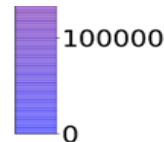
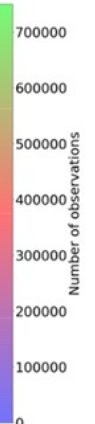
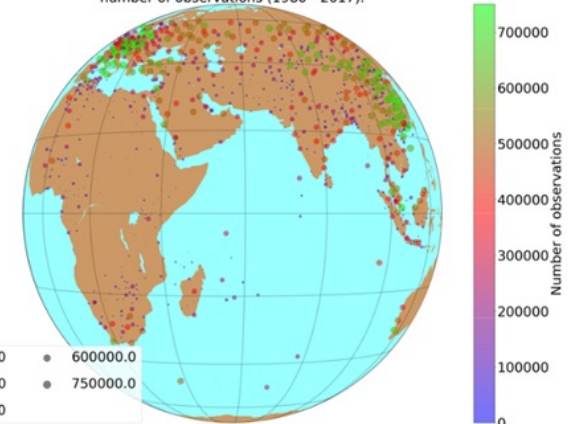
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“The Meteosats”: the European GEO satellite family

MFG
08/1981

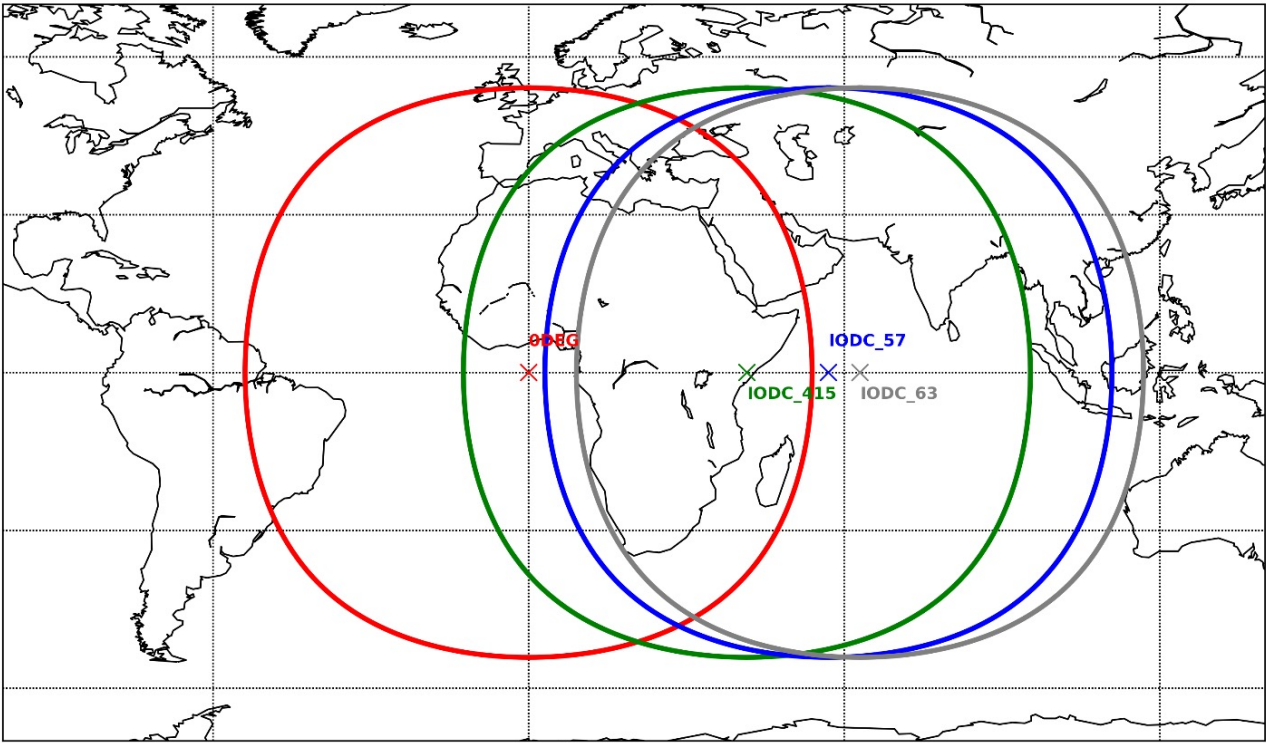
MSG
02/2004

ODEG

MET5 (MFG)
1998

63E

Meteosat field of view



MET7 (MFG)
2007

57E

MET8 (MSG)
2017

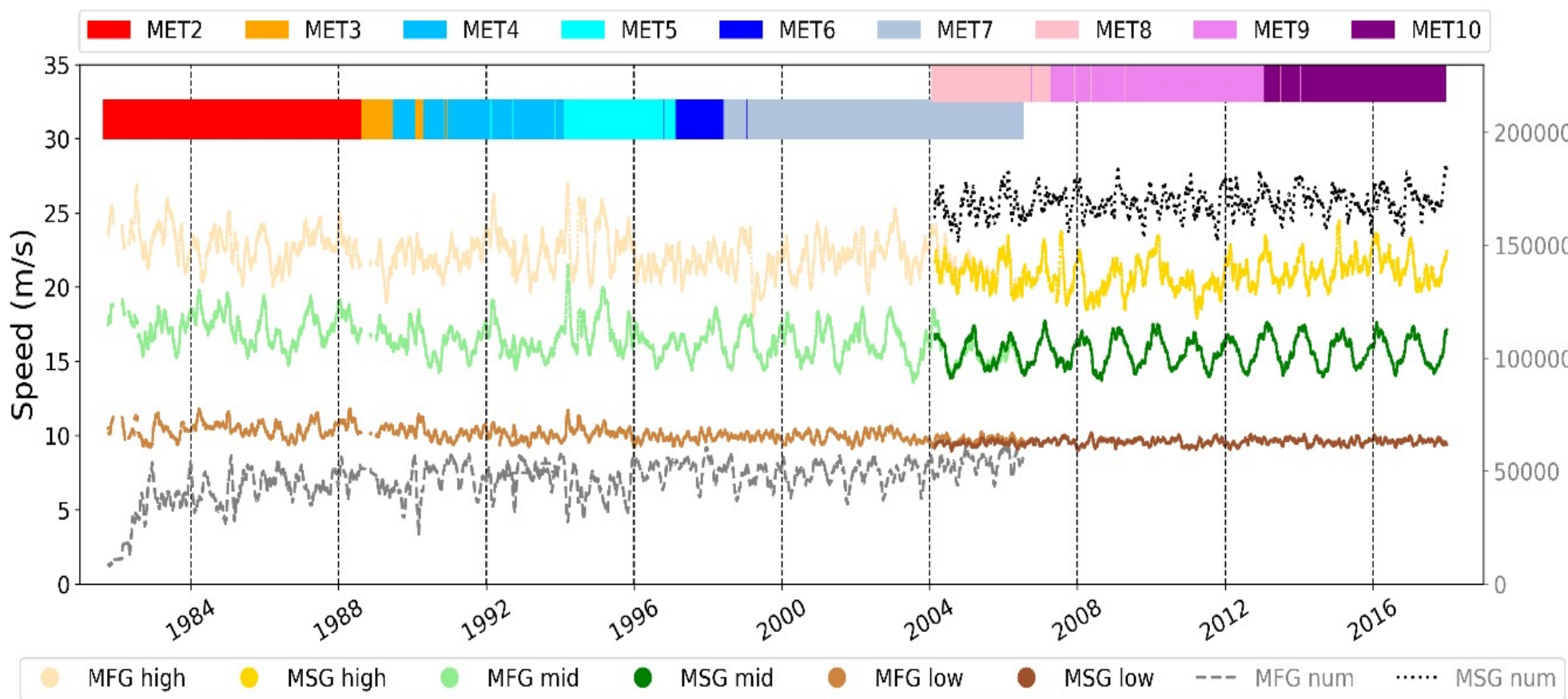
41.5E

	Rep Cycle	Bands	Pixel Size
MFG (2-7)	30 min	2 (WV/IR) 1 (VIS)	5 km 2.5 km
MSG (8-11)	15 min	11 (WV/IR/VIS) 1 (HRV)	3 km 1 km

Meteosat GEO AMV climate data record at 0°

- a unique Climate Data Record of geostationary AMV using the operational EUMETSAT algorithm adapted for time series processing;
- first AMV CDR based on cross-calibrated geostationary radiances;
- 38 years (1982-2019) years of Atmospheric Motion Vectors from 9 Meteosat satellites.

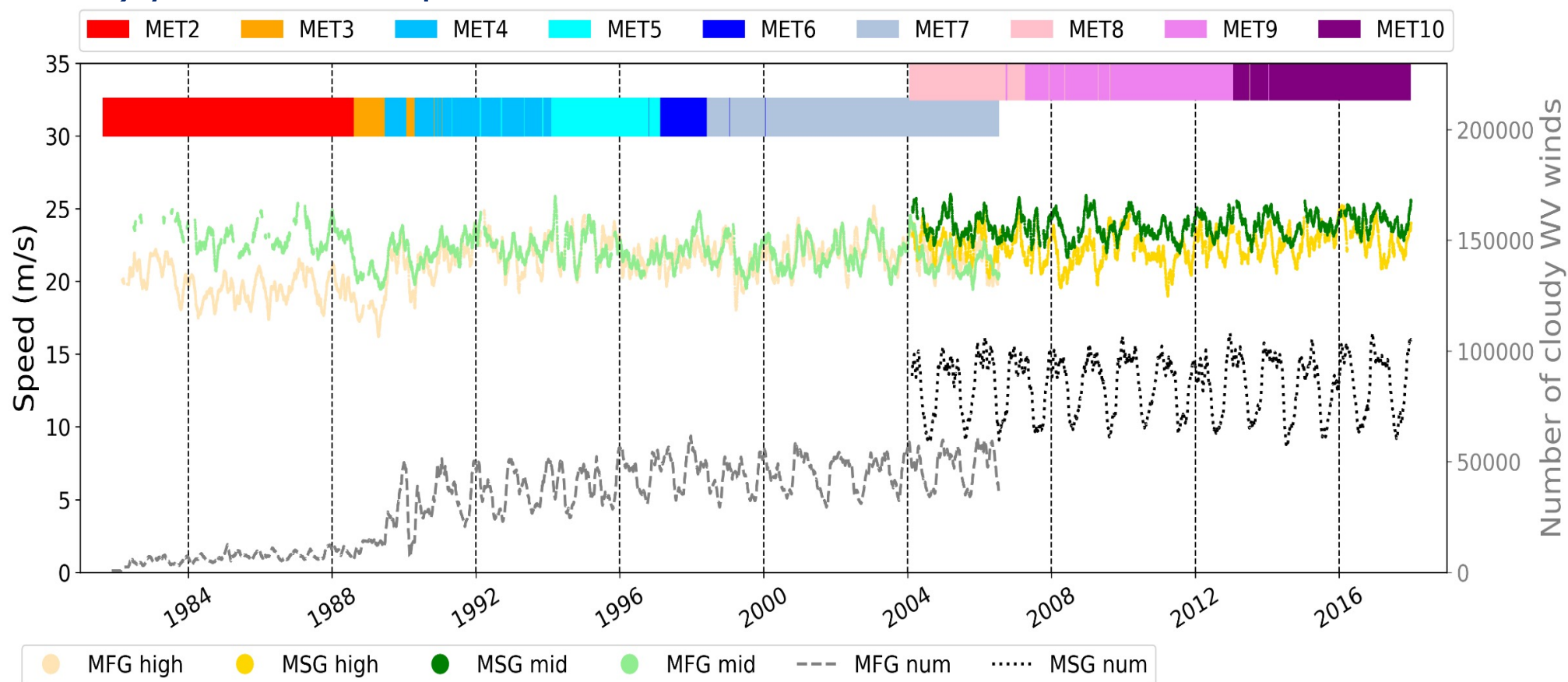
Average daily **number** of **infrared** wind vectors and their associated average **speed**



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Average daily
number of
cloudy **water**
vapor wind
vectors and their
associated
average **speed**

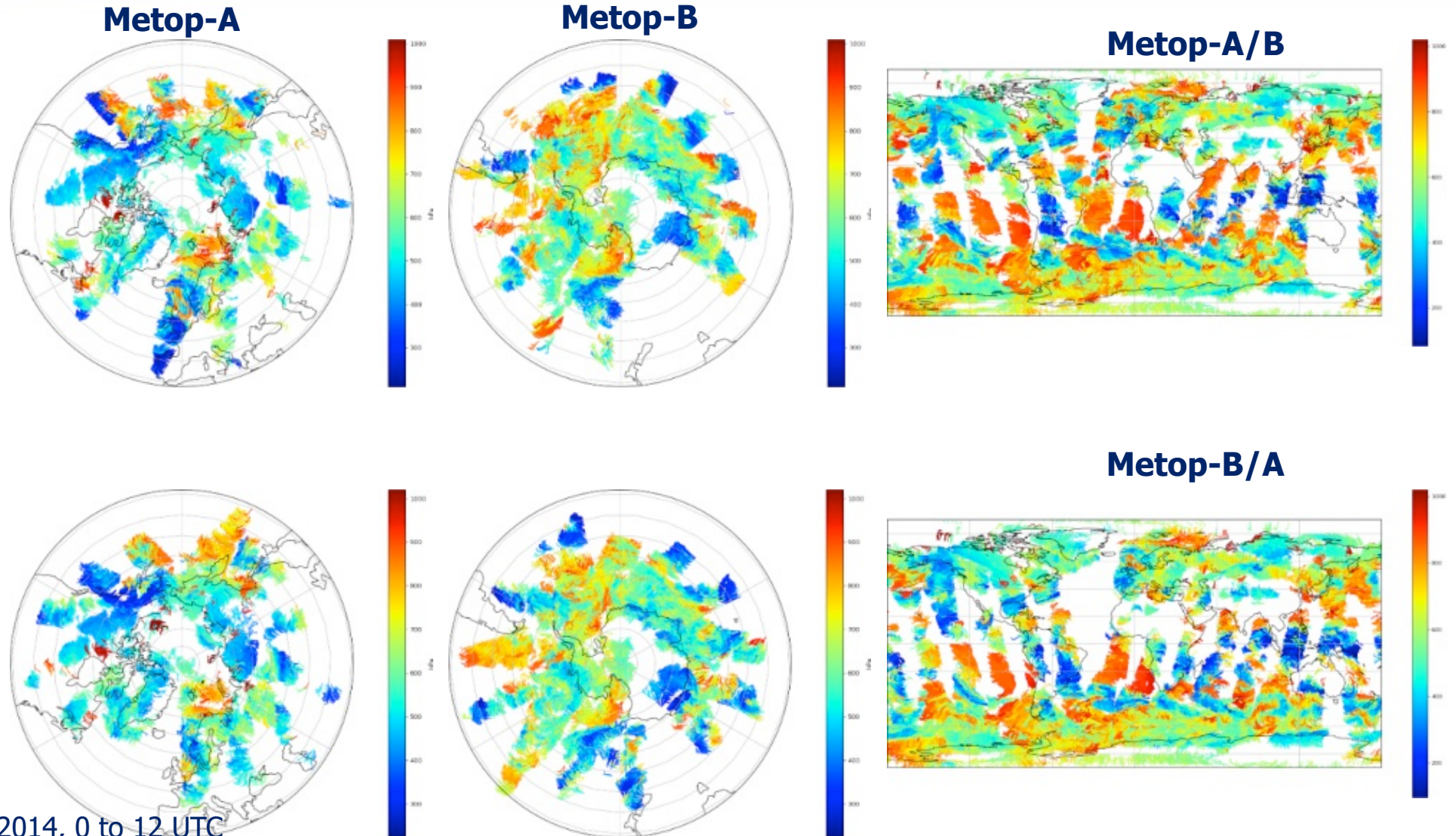


Metop (A and B) global and polar AVHRR AMV TCDR

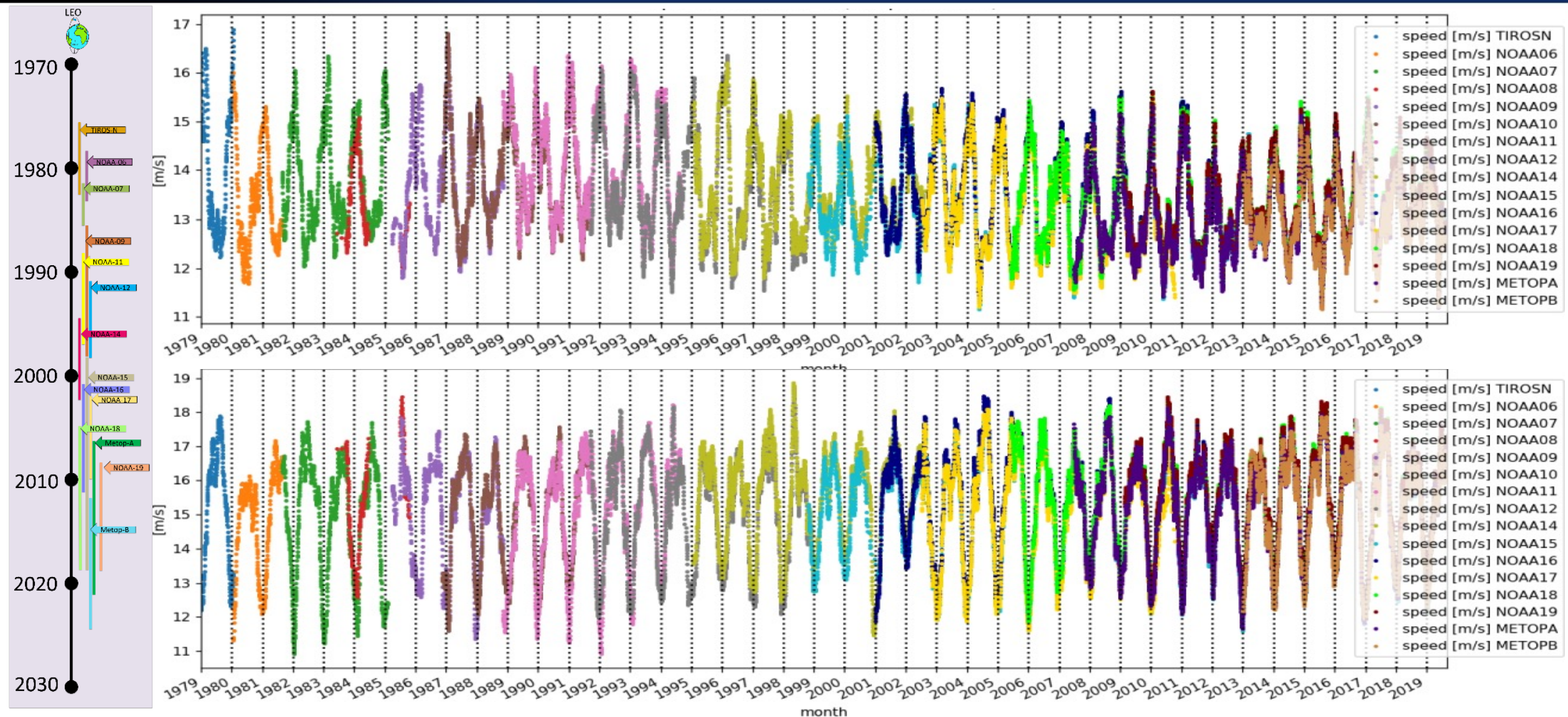
Input data:
AVHRR LAC in
channel 4

AMVs are
reprocessed using
the
EUMETSAT algorithm
using 2 orbits
allowing to retrieve
AMVs until about 45°
North and South

Example for the 1st January 2014, 0 to 12 UTC

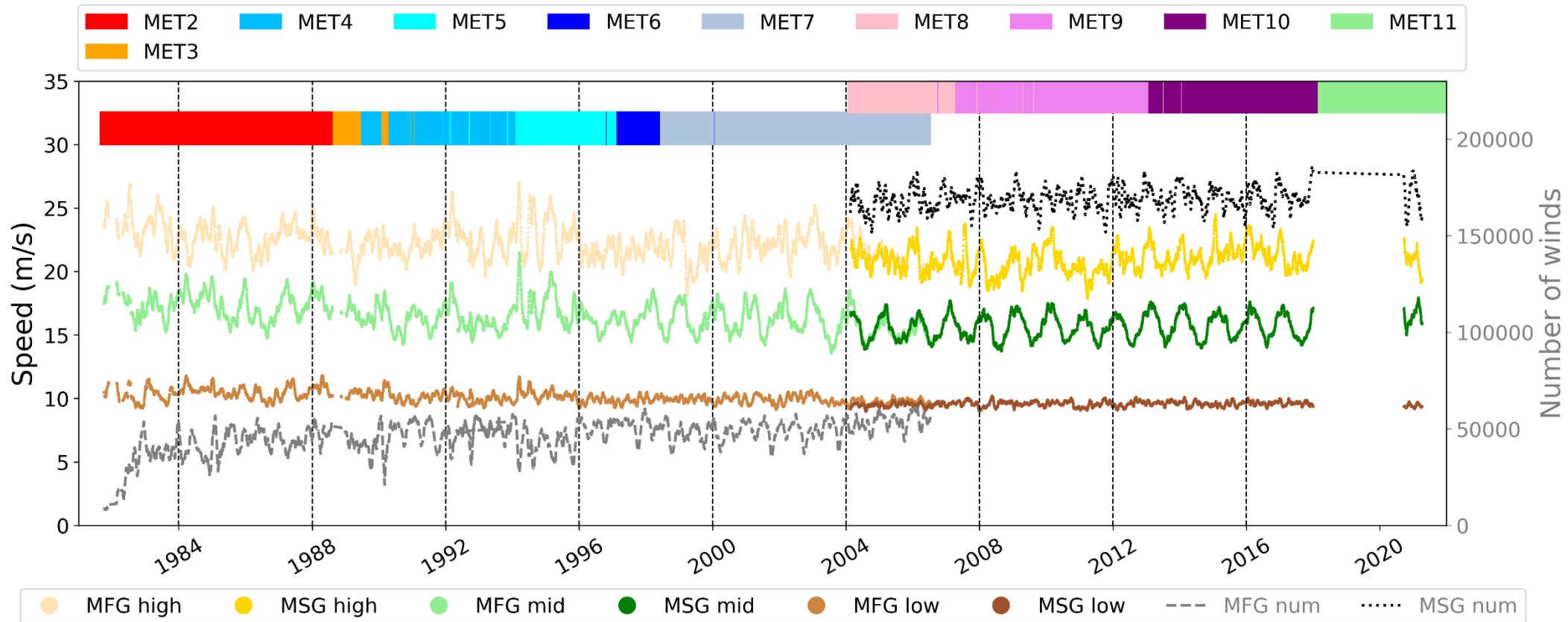


GAC AVHRR Polar AMV speed from 16 AVHRR instruments



AMVs iCDR production

MFG + MSG GEO AMV at 0°, MET11 AMVs not shown here



Future foreseen reprocessing activities at EUMETSAT

- ❑ MFG/MSG IODC
- ❑ MSG AMV using OCA cloud products

- ❑ Release 2 of AVHRR GAC AMVs

- ❑ Infrared imagers on polar-orbiters
 - Assess feasibility of generating Atmospheric Motion Vectors (AMV) from early imagers onboard polar-orbiting satellites like the Temperature-Humidity Infrared Radiometer THIR onboard Nimbus-4 to -7 e.g.
 - Generate level 2 AMV climate data records (CDRs) for the early satellite era

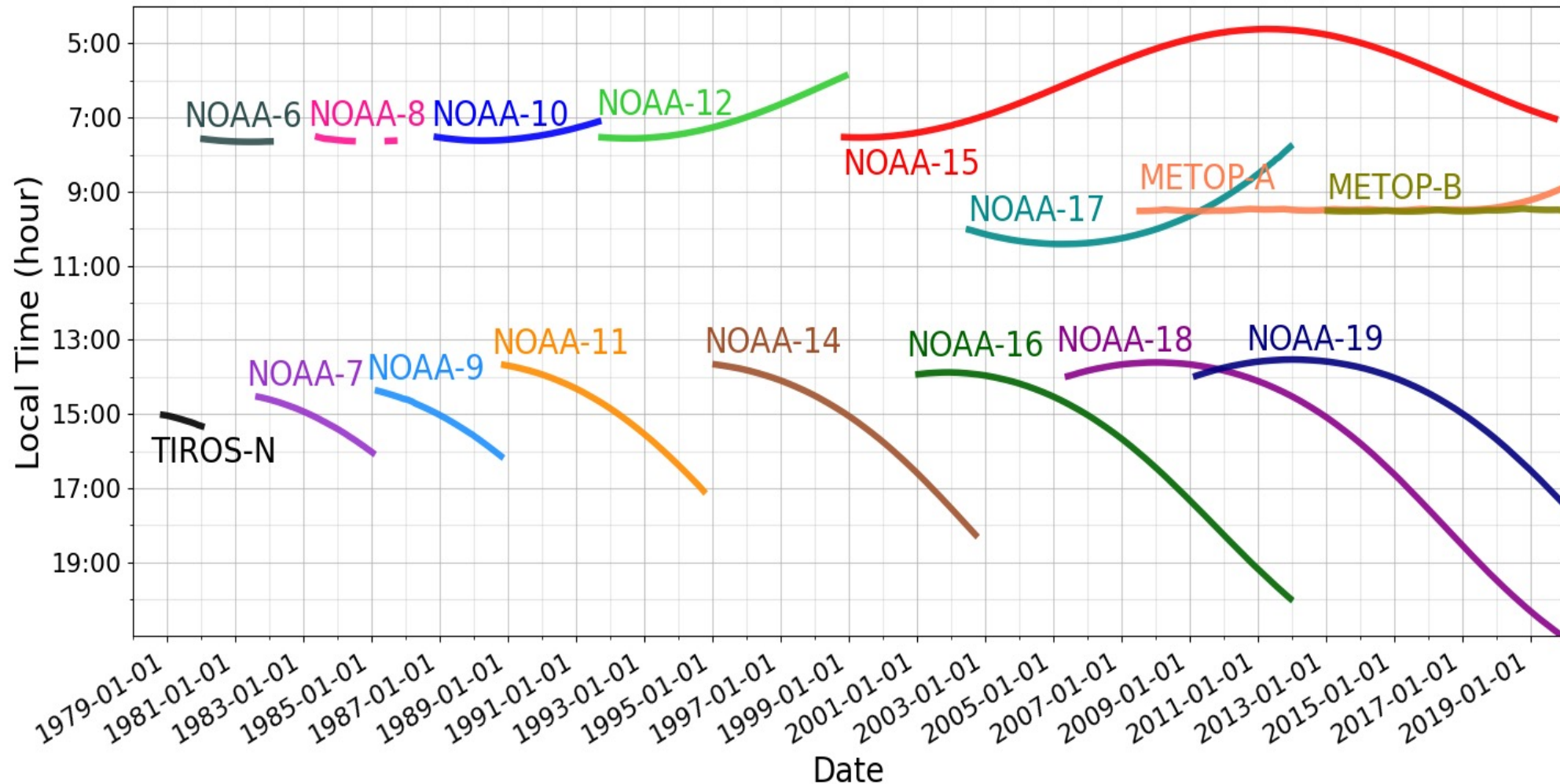
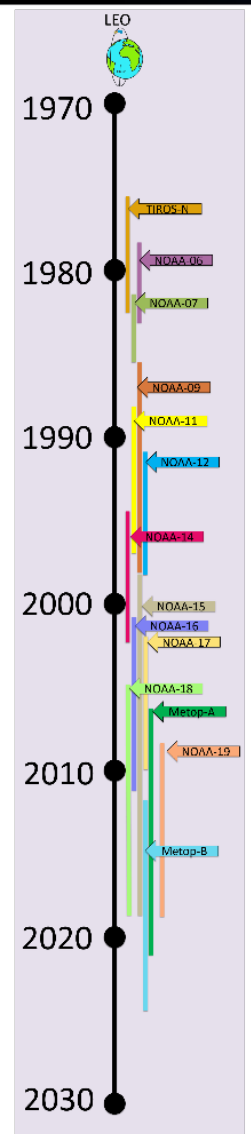
What next to for the AMV community for reprocessing?

- ❑ Upper air winds produced from geostationary and polar-orbiting satellites are an essential source of information used for the climate reanalysis. Only a few of them are or were used to produce operationally ERA-interim, ERA-5 and JRA operational reanalysis. AMVs from US (GOES), Japan (GMS, MTSAT), as well as polar AMVs using AVHRR and MODIS instruments on board US satellites.
- ❑ Currently the **ECV inventory** (<https://climatemonitoring.info/ecvinventory/> v3.0) reports only 10 dataset of upper-air winds climate ECV (It is very a very small number considering the number of instruments potentially suitable to derive AMVs. To add planned or released CDR please email: ecv_inventory@eumetsat.int)
- ❑ To achieve a higher geographical coverage the development of a **multi-instrument AMV products** could be an option for the future. The already existing CIMSS LEO-GEO AMV data record is an example. However combining different instrument datasets is not necessarily the solution as the time difference between images in case of multi-instrument will affect the number of derived vectors. For assimilation purpose, it is probably simpler to ingest several individual datasets. Ideally having a unique GEO-ring AMV product + a polar AMV dataset could be the goal
- ❑ Would it be better to have many **single sensor** data having different biases **or** if one should construct a **global AMV dataset** (that may enable more usage than only assimilation)?

The end

Thank you 😊

NOAA AVHRR Polar AMV



Daily AMV speed over each pole from the 16 AVHRR

